



Solar Splash

Senior Project I Presentation

December 2nd, 2020



Advisors:

Dr. Norman Asper
Dr. Karen Yan
Regina Cadillac

Lauren DeSimone
Daniel Johnson (DJ)
Eliza Sweet
Christopher Taylor

Volunteer:

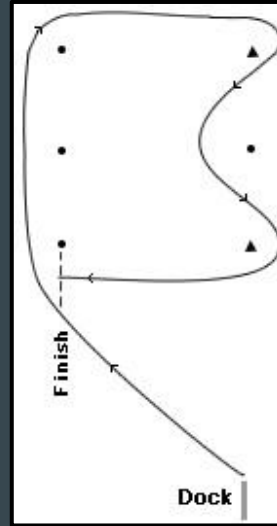
Nick Moriello

Solar Splash Competition

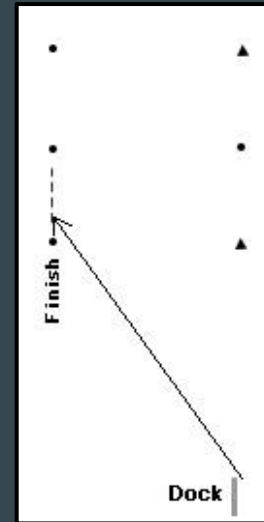
- Springfield, Ohio
- June 8th-12th, 2021

Competition Events

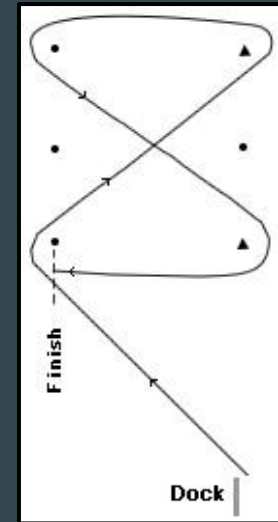
- Qualifying - Eligibility
- Endurance - Efficiency (2000 meters)
- Sprint - Maximum Speed (300 meters)
- Slalom - Maneuverability



Endurance Qualifier



Sprint Qualifier



Slalom



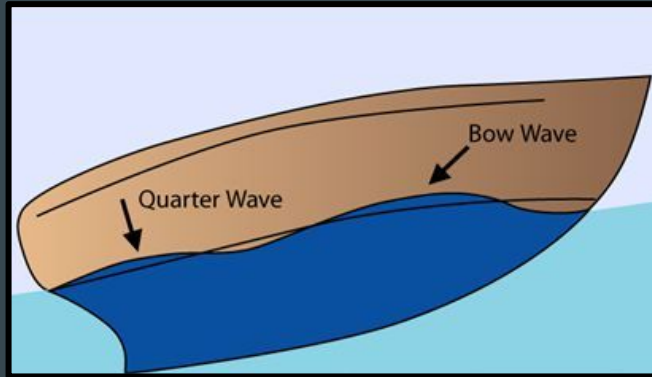
Weight Distribution & Hull



Lauren DeSimone

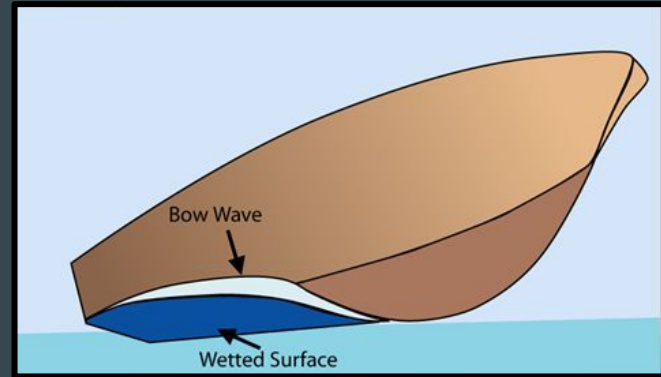
Weight Distribution Objective

Displacement Hull



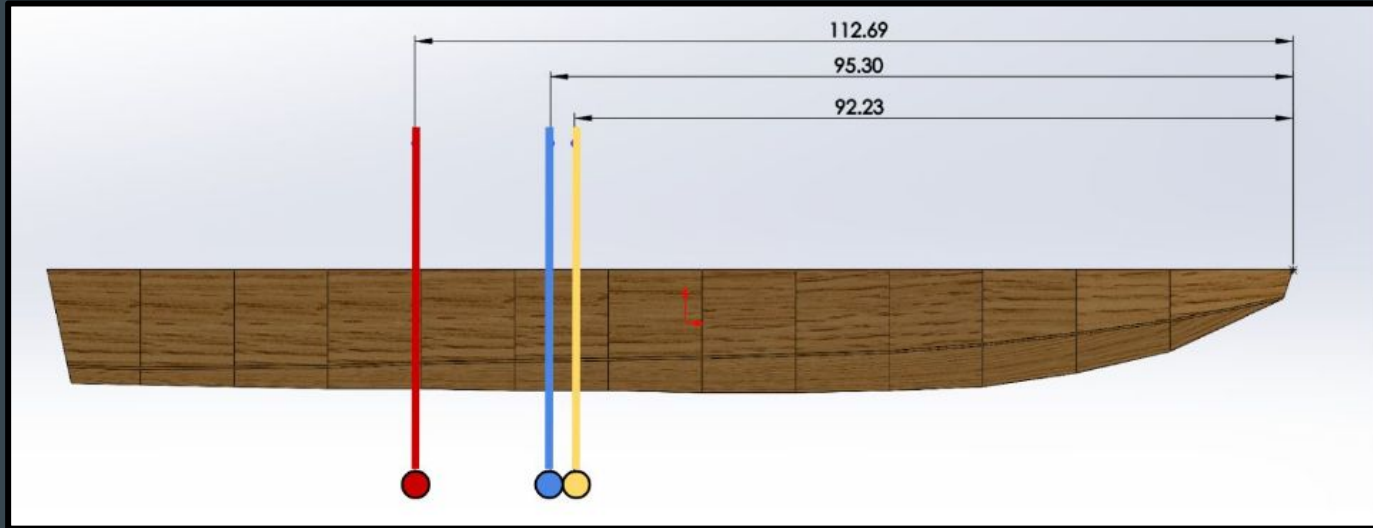
- Endurance Event
- Greater Range
- Requires less power from motor
- More comfortable

Planing Hull



- Sprint and Slalom Event
- Generates Lift
- Good maneuverability
- Higher Speed

Previous Weight Distribution



Sprint COG



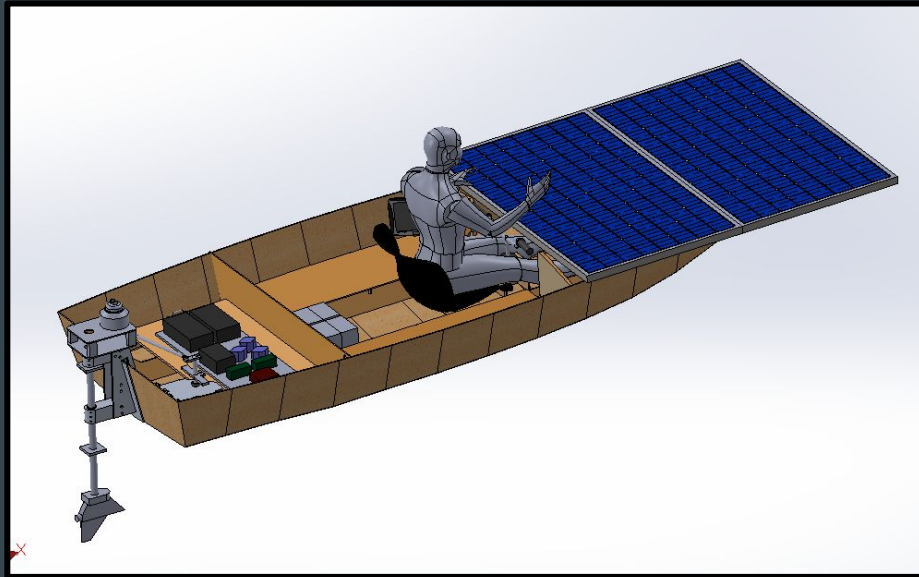
Center of Flotation



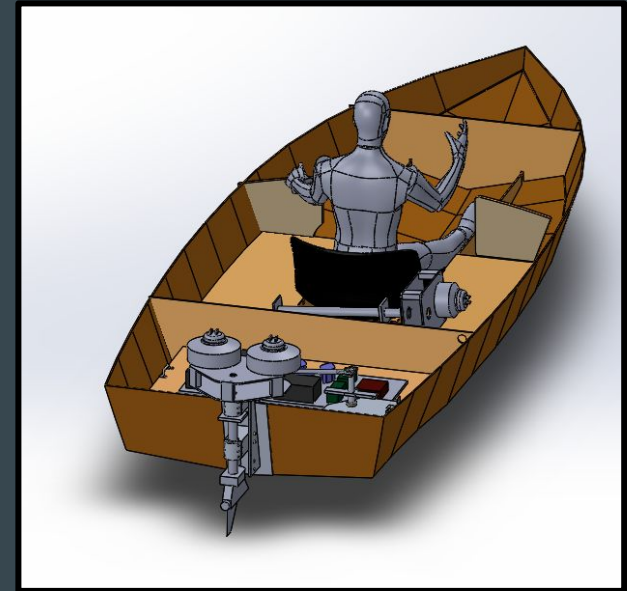
Endurance COG

New Weight Distribution Schematics

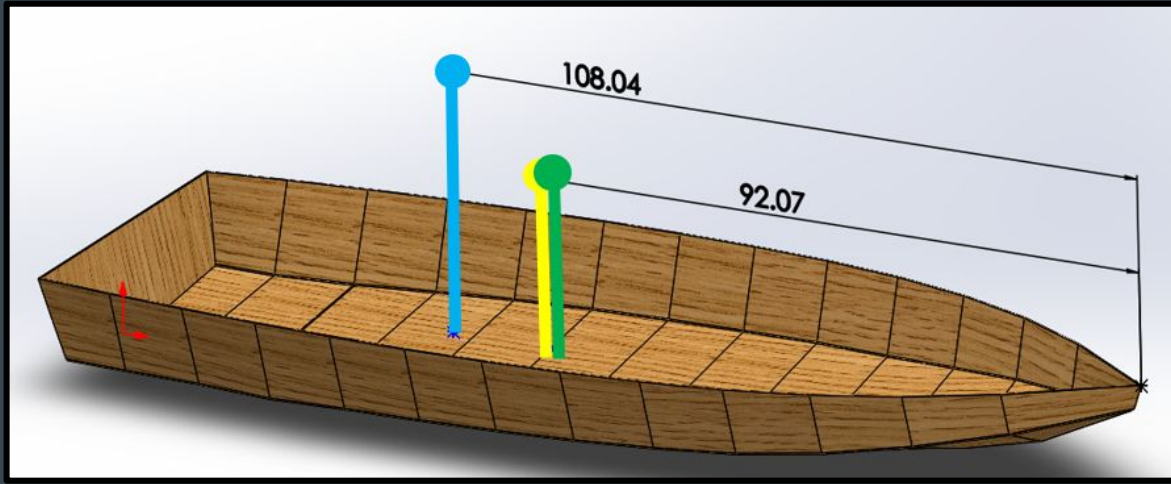
Endurance Event
Displacement Hull



Sprint/Slalom Event
Planing Hull



New Weight Distribution



Sprint COG



Center of Flotation



Endurance COG

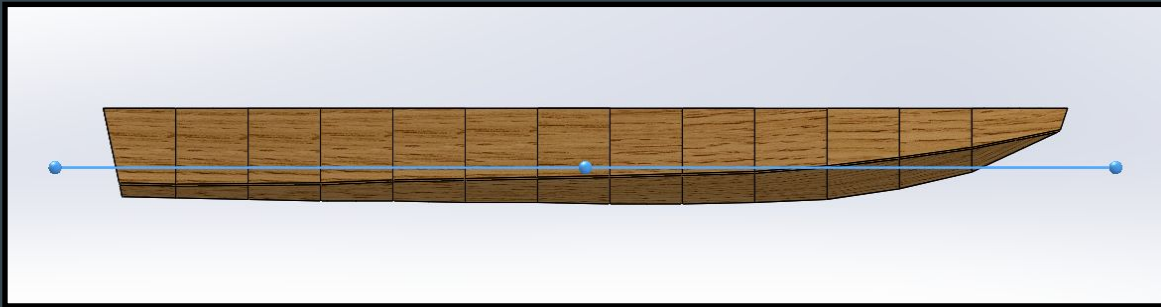
COG Calculations

Sprint				
Part	Weight of Part (lb)	Distance from Bow (in)	Moment (lb*in)	
Electrical Panels	40	136	5440	
Batteries	80	109.5	8760	
Seat	3	81	243	
Driver	145	81	11745	
Steering	4	75	300	
Ballast	9.3	61	567.3	
Foam (Bow)	7.5	17.5	131.25	
Foam (Decking)	8.1	99	801.9	
Fire Extinguisher	3.25	73	237.25	
Toughbook	2	75	150	
Telemetry Battery	4	69	276	
Sprint Motor	60	161	9660	
Endurance Motor	41	101	4141	
Motor Mount	10	161	1610	
Block Mount	10	161	1610	
Driveshaft	4	161	644	
Propeller	9	161	1449	
Propeller Unit	4	161	644	
Stored Propeller	9	61	549	CoG (in)
	453.15		48958.7	108.041

Endurance				
Part	Weight of Part (lb)	Distance from Bow (in)	Moment (lb*in)	
Electrical Panels	40	136	5440	
Batteries	80	107	8560	
Solar Panel 1	34	32	1088	
Solar Panel 2	34	70	2380	
Seat	3	81	243	
Driver	145	81	11745	
Steering	4	75	300	
Ballast	9.3	81	753.3	
Foam (Bow)	7.5	17.5	131.25	
Foam (Decking)	8.1	99	801.9	
Fire Extinguisher	3.25	73	237.25	
Toughbook	2	75	150	
Telemetry Battery	4	69	276	
Sprint Motor	60	45	2700	
Endurance Motor	41	161	6601	
Motor Mount	10	161	1610	
Block Mount	10	161	1610	
Driveshaft	4	161	644	
Propeller	9	161	1449	
Propeller Unit	4	161	644	
Endurance Extension	1	161	161	
Stored Propeller	9	61	549	CoG (in)
	522.15		48073.7	92.069

Flotation & Buoyancy

- Competition Constraint : 120% Flotation
- 3.02 ft³ of foam needed
- Currently 7.80 ft³ of foam
- 2.6 Safety Factor



Waterline in Solidworks

Part	Weight of Part (lb)
Electrical Panels	40
Batteries	80
Solar Panel 1	34
Solar Panel 2	34
Seat	3
Driver	145
Steering	4
Ballast	9.3
Foam (Bow)	7.5
Foam (Decking)	8.1
Fire Extinguisher	3.25
Toughbook	2
Telemetry Battery	4
Sprint Motor	60
Endurance Motor	41
Motor Mount	10
Block Mount	10
Driveshaft	4
Propeller	9
Propeller Unit	4
Endurance Extension	1
Stored Propeller	9
Hull	225
Misc.	20
Total	782.75

Future Steps

- Remove dashboard and pedal
- Construct foam mounts for motors



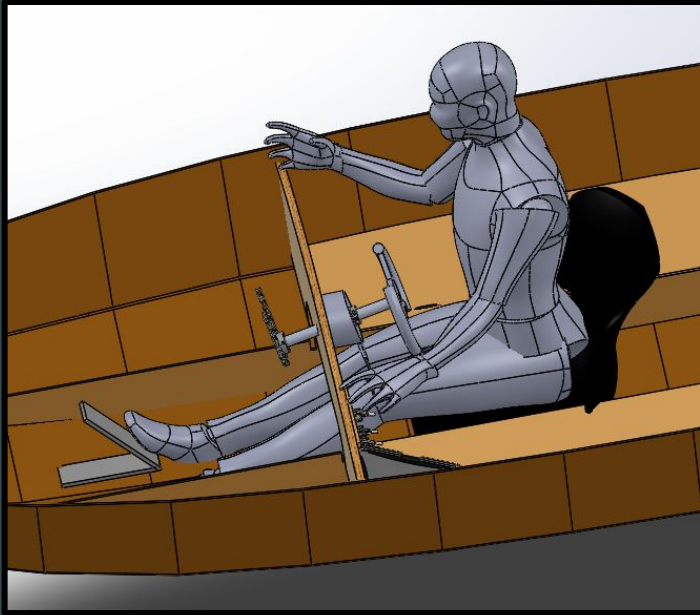


Steering

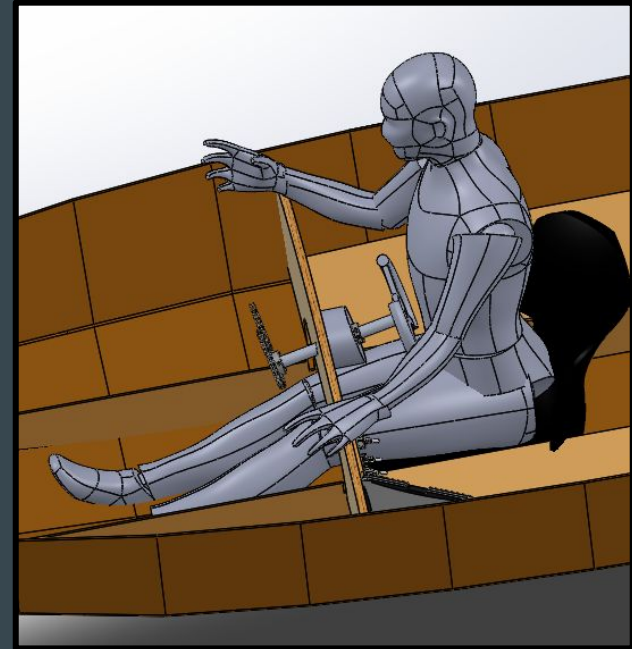


Lauren DeSimone

Steering Objective



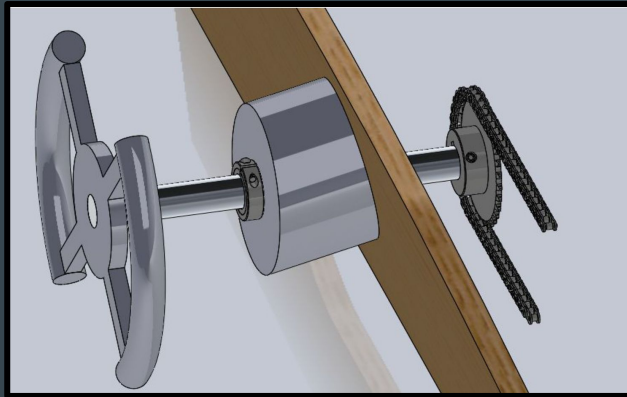
Current Design



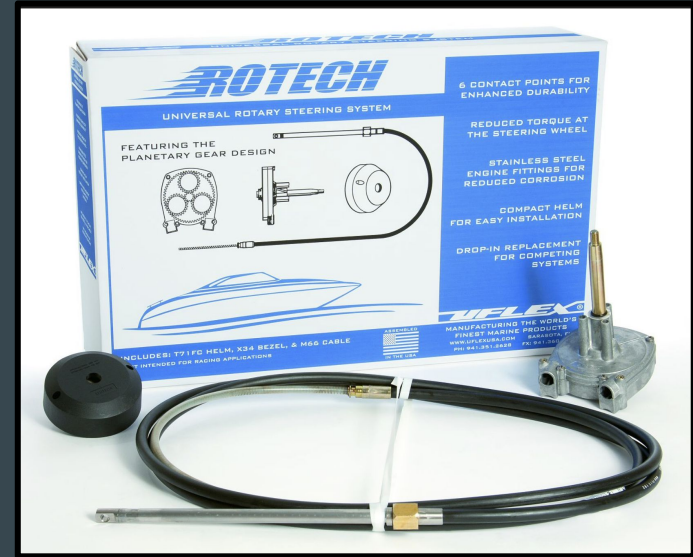
New Design, Skipper 7" up

Steering Improvements

- Chain & Sprocket -----> Push Pull Cable
 - Increased Safety
 - Better Mechanical Advantage

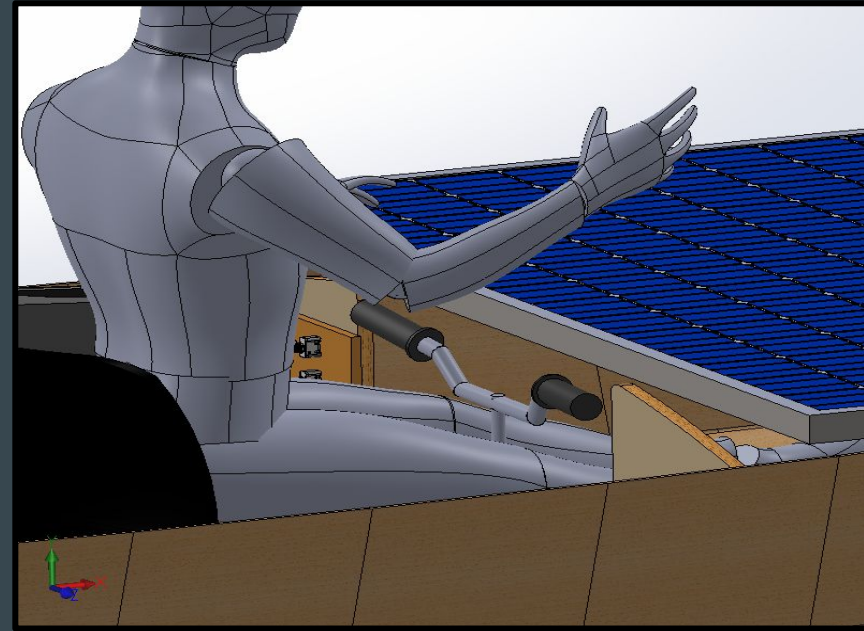
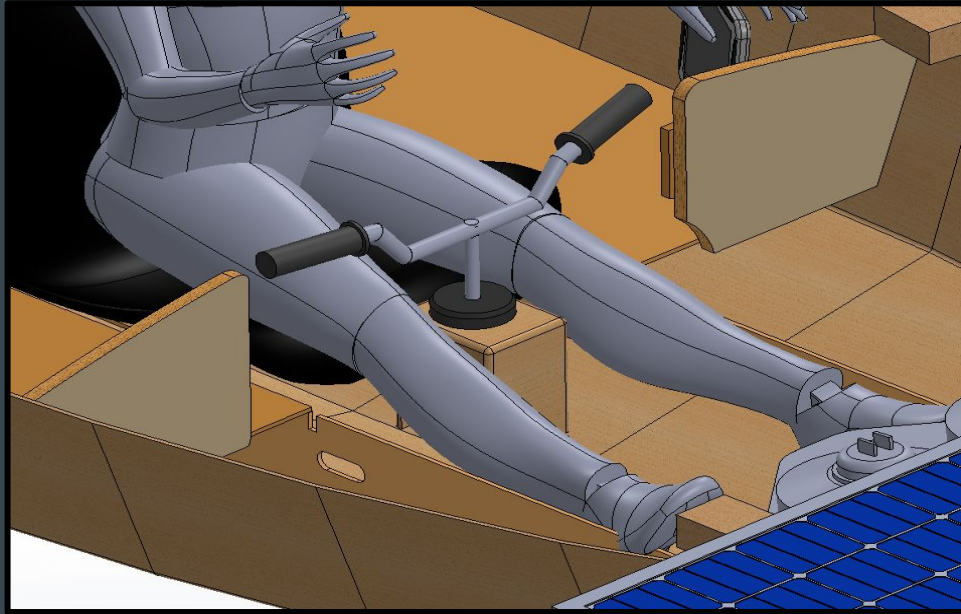


Previous Chain & Sprocket Design



Push Pull Cable

Steering Design

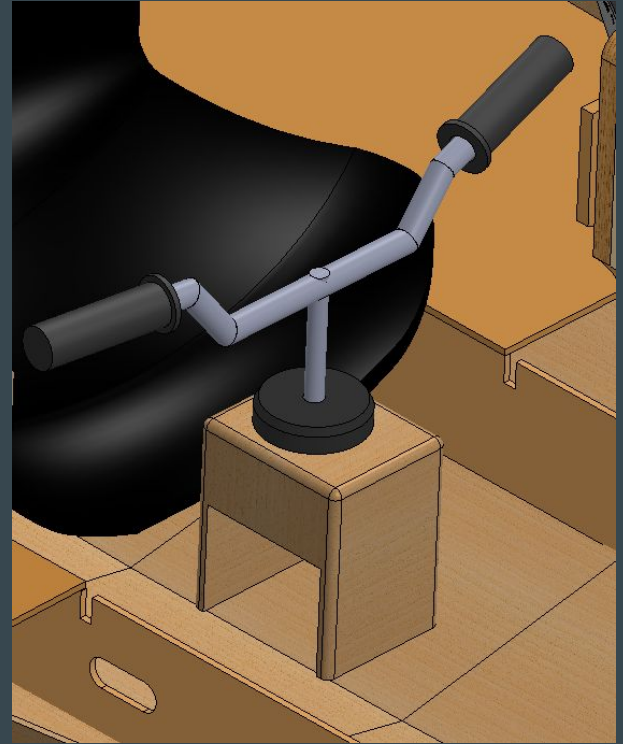


Future Steps

- Construct steering post
- Reshape handlebar
- Install Steering Cables



Handlebar from Inventory



Wooden Steering Post



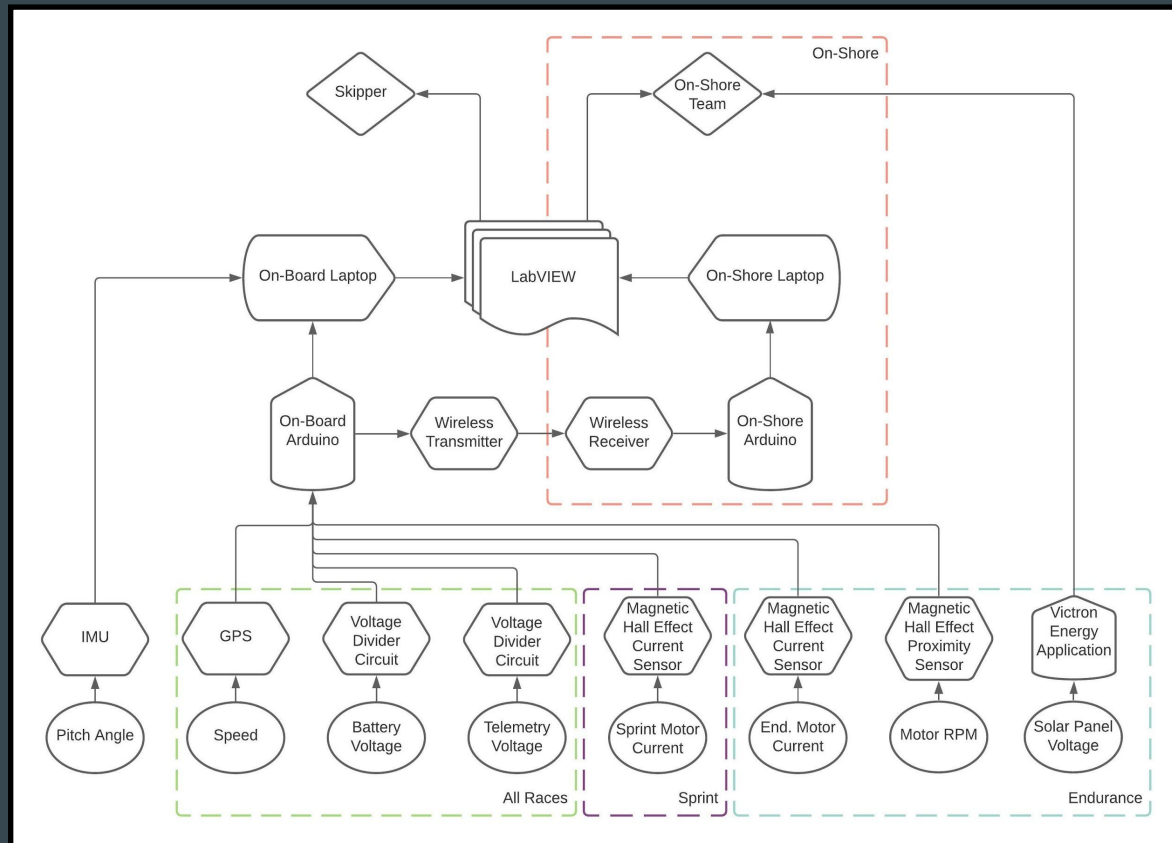
Telemetry System



Eliza Sweet

Goals & System Flowchart

1. Optimized Data Acquisition
2. Optimized Synchronous Feedback
 - LabVIEW
3. Implemented Asynchronous Feedback
 - MATLAB



Telemetry Data Collection Flowchart

Preliminary Testing & Optimization

- Hardware/Software Compatibility & Optimization
 - GPS
 - IMU
- Hardware Constraints
 - Voltage Dividers

Optimal Voltage Divider Hardware to Eliminate Microcontroller Damage

Hardware	V_{in} (V)	V_{out} (V)	R_1 (Ω)	R_2 (Ω)
Batteries	36	3.87	83k	10k
Telemetry Battery	12	4.00	10k	5k
Sprint Current	16	3.81	64k	20k
Endurance Current	16	3.95	61k	20k
Endurance Motor RPM	30	4.00	26k	4k

GPS Data

Time: 05:44:03

Date: October 21, 2020

Status: A

Fix Type: 3

Satellites in View: 09

Latitude (deg): 39.832567 N

Longitude (deg): 74.748050 W

Elevation (m): 184.0

Ground Speed (km/hr): 0.47

Ground Speed (knots): 0.25

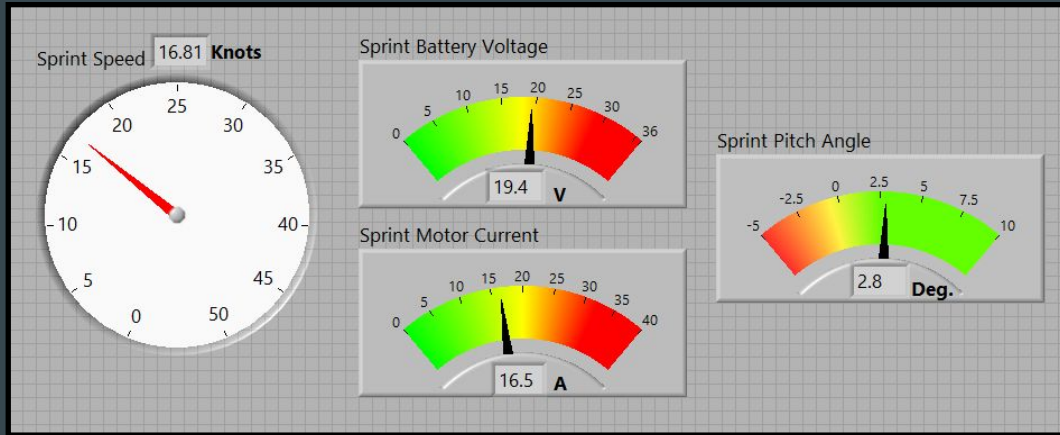
Course over ground (deg): 343.22

GPS LabVIEW Output

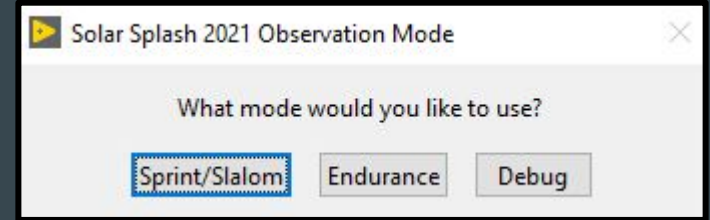
return type	station
1	-129.99€
handle	9.81404
1	2.28508
	0
	0
	0
	0
	5.43501

IMU LabVIEW Output

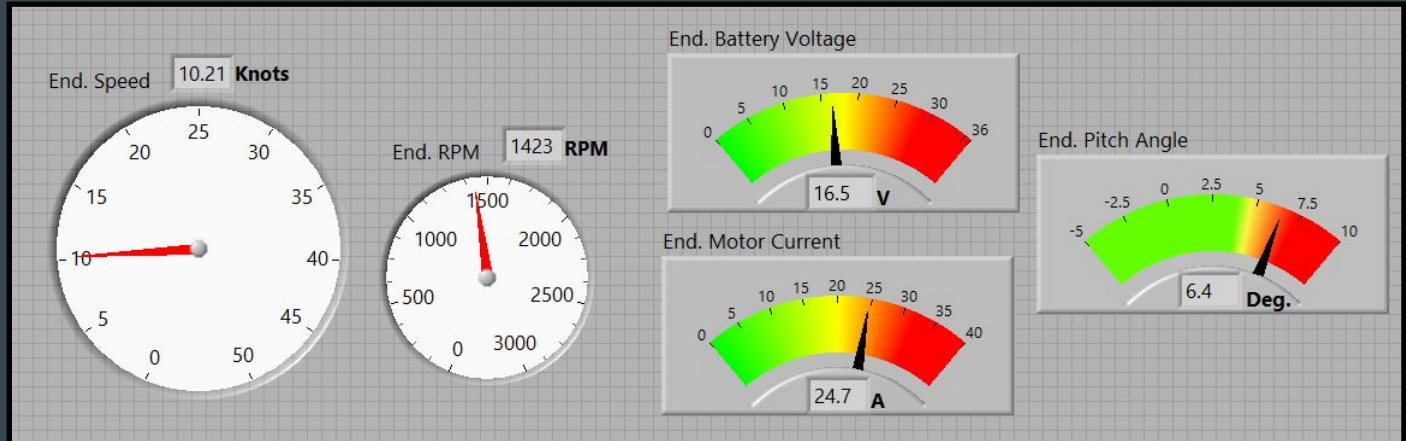
Synchronous Feedback Optimization



Sprint/Slalom UI



Mode Selection UI



Endurance UI

Upcoming Manufacturing & Implementation

1. Rewire & relabel entire system
2. Implement all current and motor RPM sensors
3. Assemble IMU housing
4. Wire pump
5. Program LabVIEW and MATLAB

	TASK TITLE	Member	% OF TASK COMPLETE	WINTER 2020-2021				SPRING 2021												SUMMER 2021											
				DECEMBER				JANUARY				FEBRUARY				MARCH				APRIL				MAY				JUNE			
				1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
4	Manufacturing																														
4.7	Telemetry Installation	E	1%																												
4.7.1	<i>Rewire and Relabel</i>	E & D	0%																												
4.7.2	<i>Hall Effect Sensors</i>	E	0%																												
4.7.3	<i>Assemble IMU Housing</i>	E	0%																												
4.7.4	<i>Wire Pump</i>	E	0%																												
4.7.5	<i>Program LabVIEW</i>	E	5%																												
4.7.6	<i>Program MATLAB</i>	E	0%																												
5	Integration and Testing																														
5.1	Telemetric Integration	E	0%																												
5.2	Skipper Practice	T	0%																												
5.3	Endurance Practice	T	0%																												
5.4	Sprint Practice	T	0%																												

Telemetry Manufacturing and Integration & Testing Gantt Chart for Spring 2021

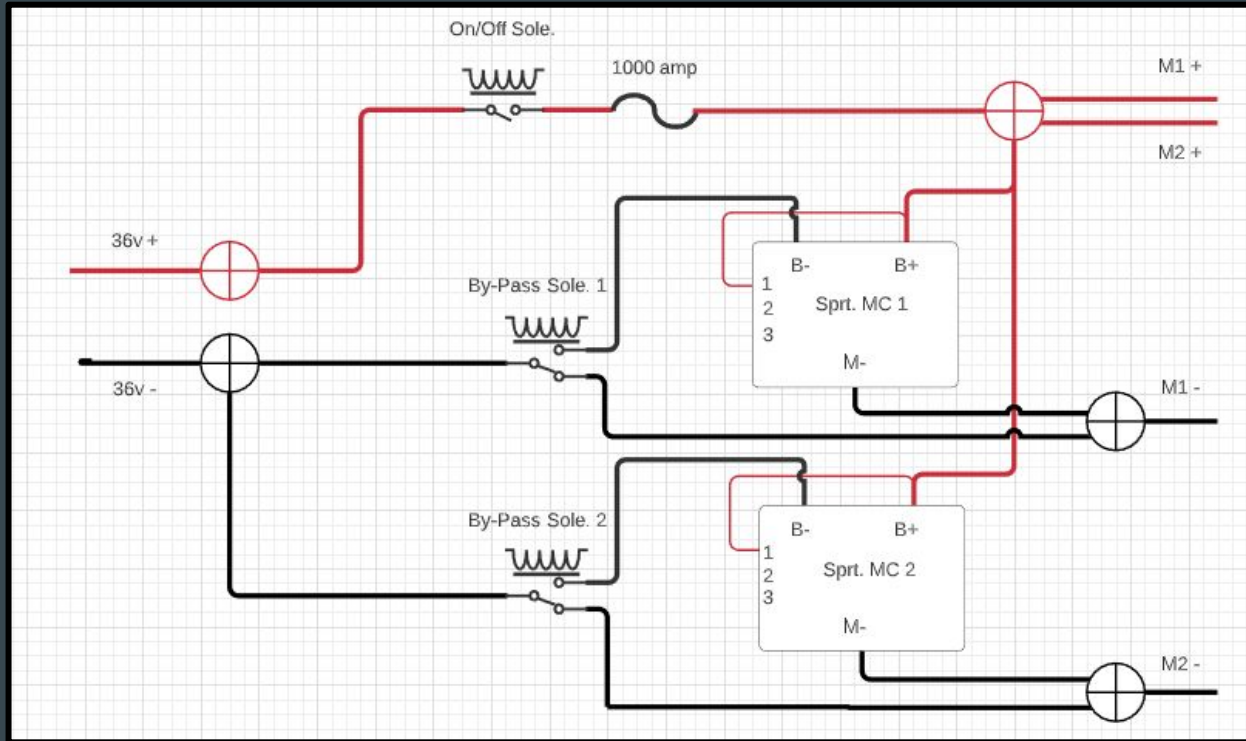


Electrical System



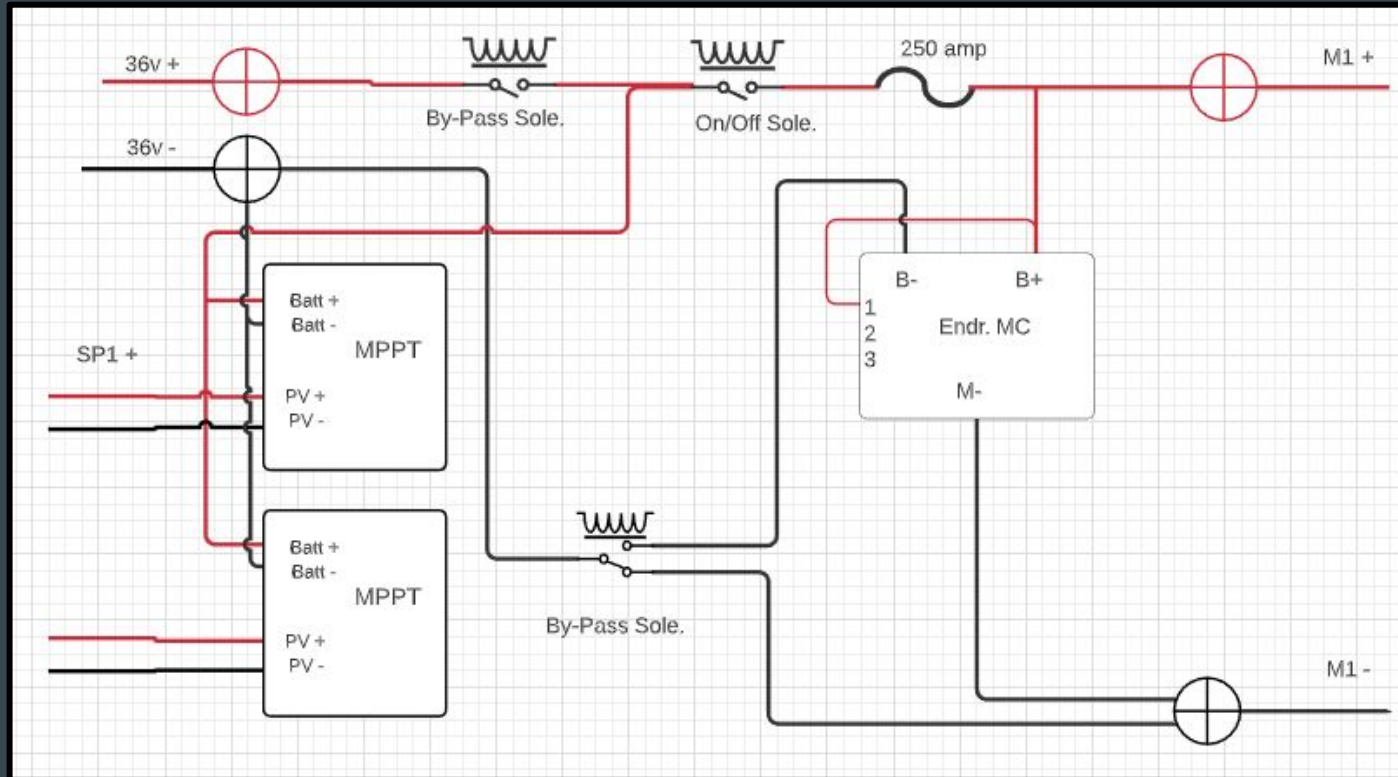
Daniel Johnson (DJ)

Sprint Configuration



2020-2021 Sprint Configuration

Endurance Configuration



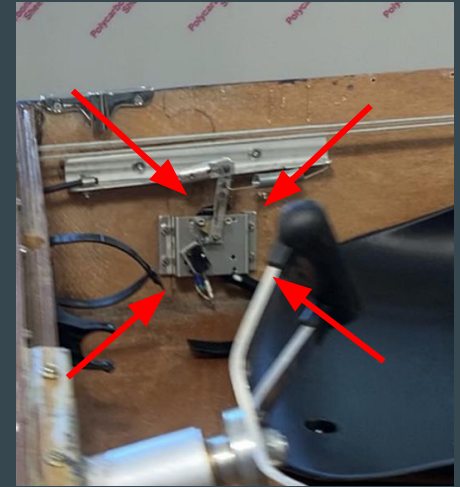
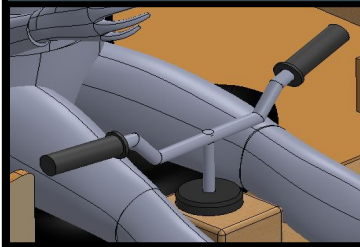
Speed Control and Bypass



2019-2020 Pedal



2020-2021 Steering wheel and Throttle

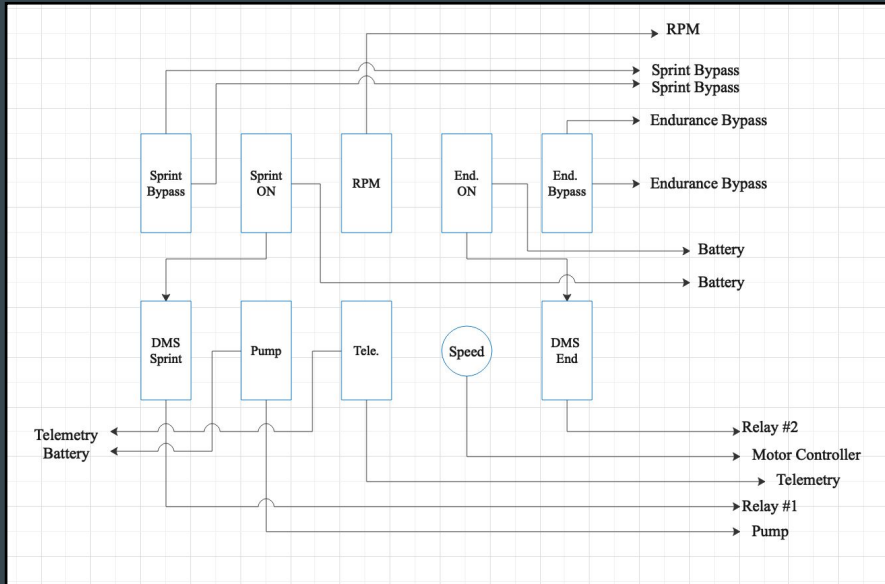


2019-2020 Potentiometer and Micro switch

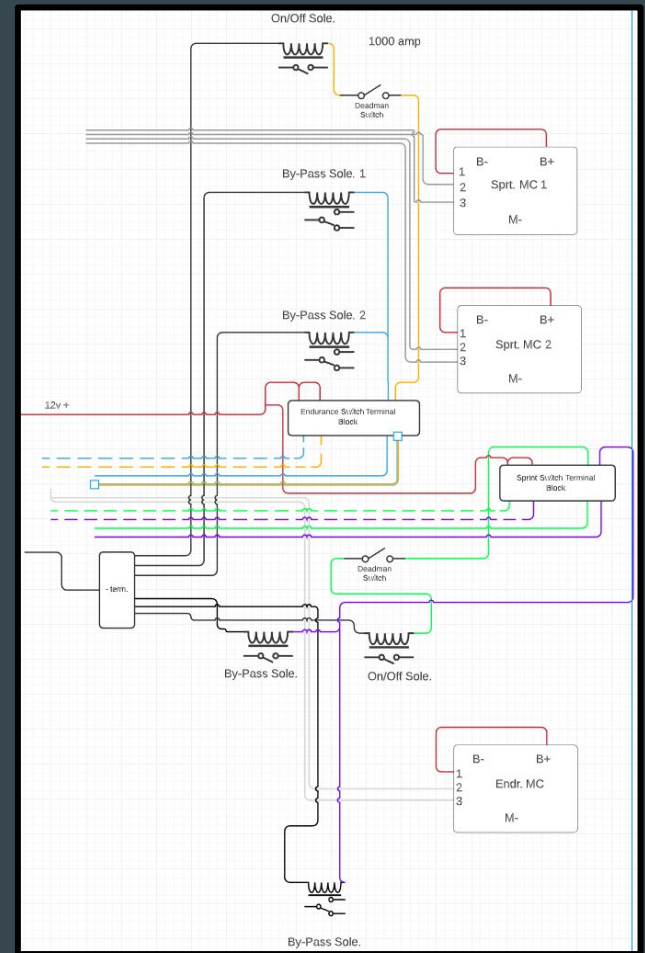
Switch Control



2019-2020
On-Board Switch
Panel



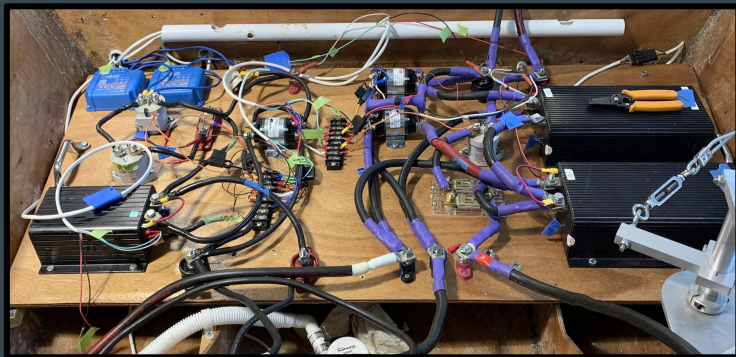
2020-2021 Switch
Panel Schematic



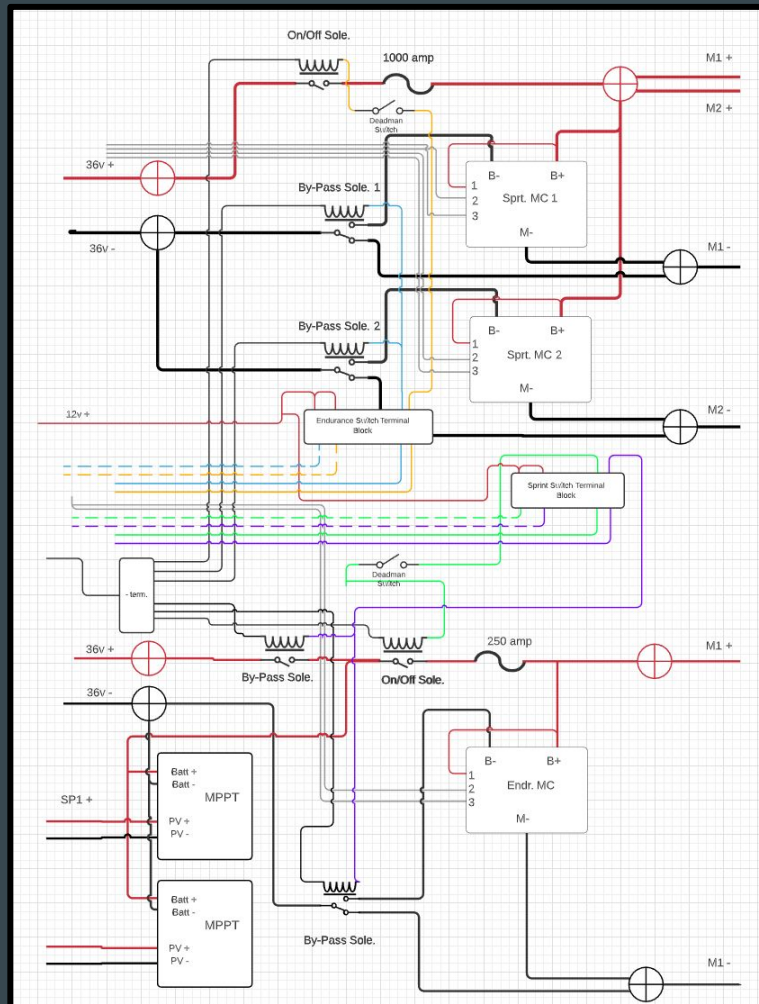
2020-2021 Switch Board wiring

Overall Layout

- Improve wire organization
 - Wire hooks and clamps
 - Label
- Polycarbonate cover
- Motor controller board supports



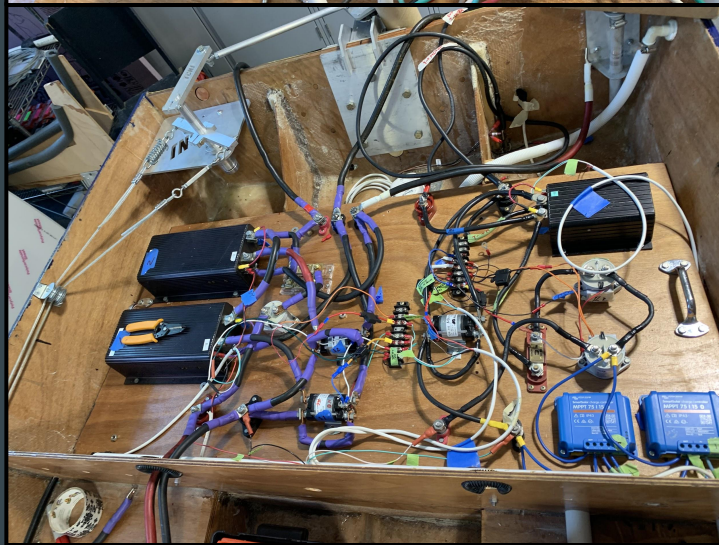
2019-2020 Electrical Board



2020-2021
Electrical
Board Layout

Future steps

- Re-Build Electrical Board
- Single Pull Throttle Implementation
- On-Board Control Completion
- Wire Organization
- Polycarbonate Cover
- Wooden Board Supports





Motor Mounts



Christopher Taylor

Motor Mounting

1. Updated Blocks
2. Improved Mounting Plates
3. Wedge Tilt System

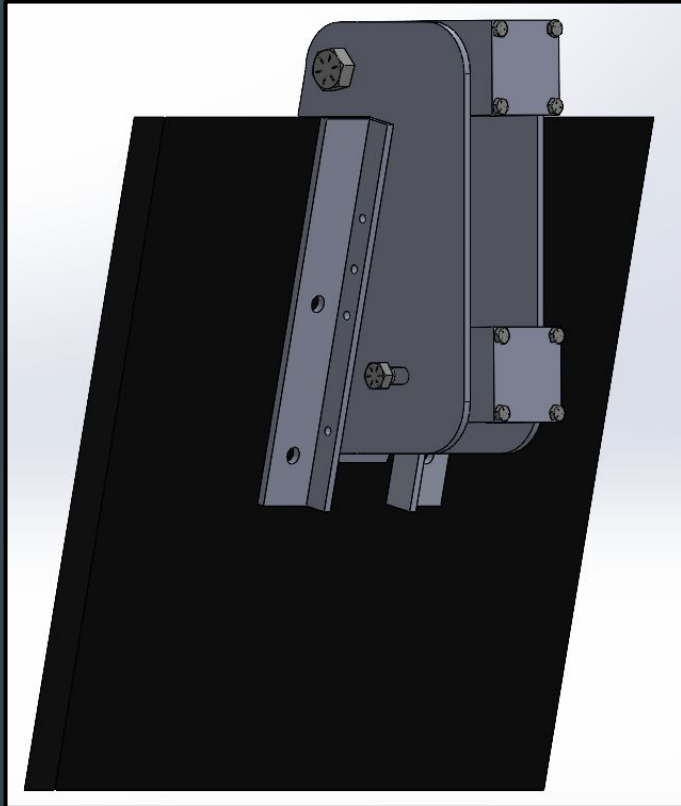


2019-2020 Mounting
Configuration Side View (Right)

2019-2020 Mounting
Configuration Top View (Left)

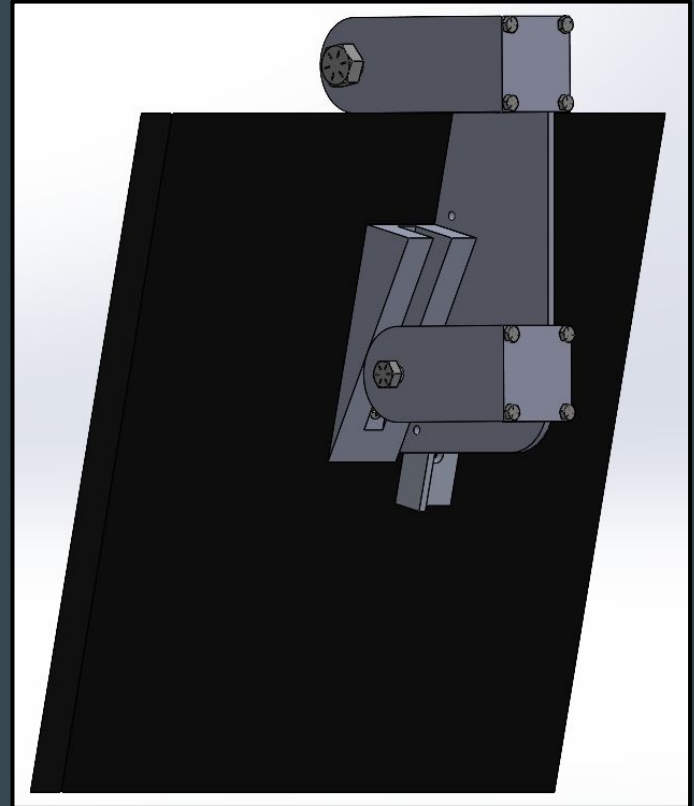


Motor Mounting

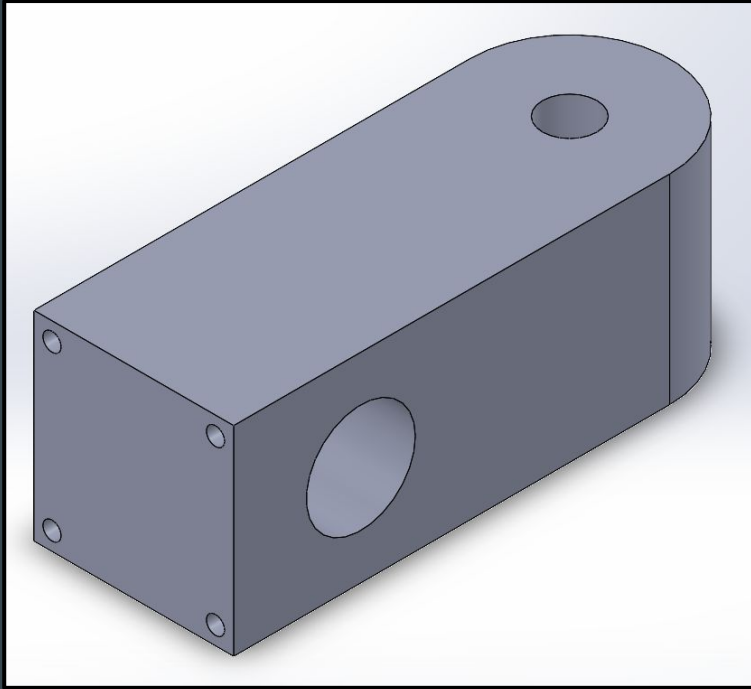


2020-2021 Mounting
Configuration (Left)

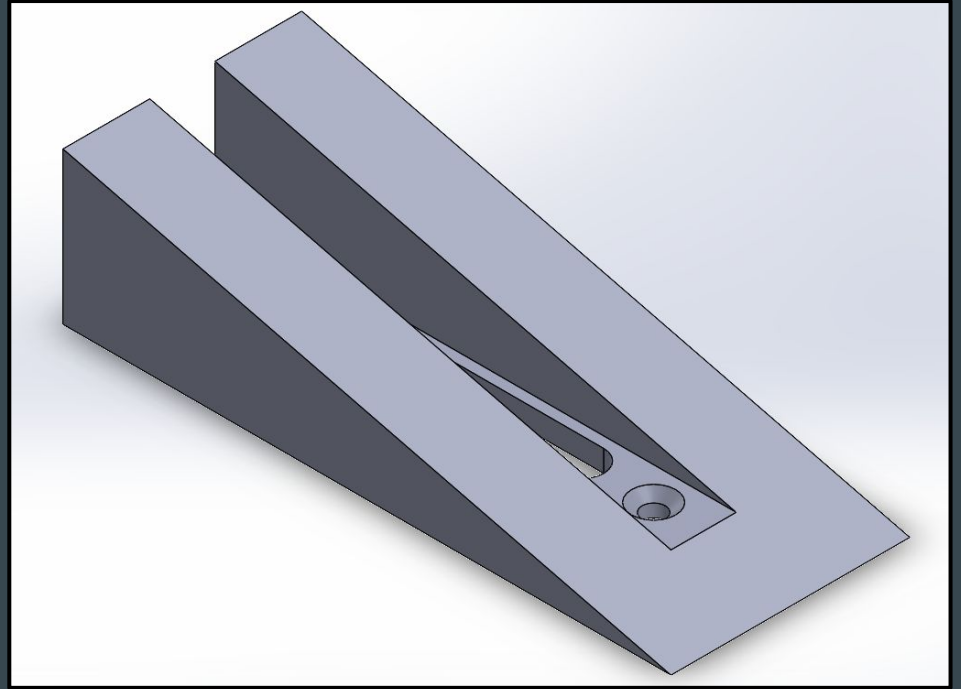
2020-2021 Wedge
Configuration (Right)



Motor Mounting



2020-2021 Mounting Blocks



2020-2021 Tilting Wedge

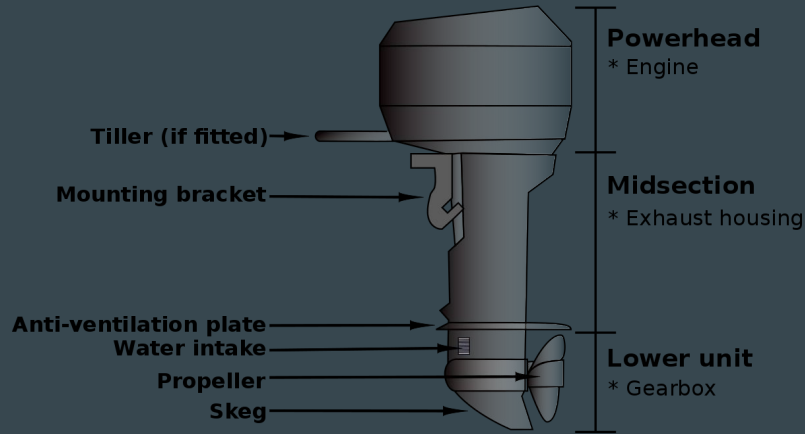


Power Transfer Unit



Christopher Taylor

Power Transfer Unit



Outboard Motor Components

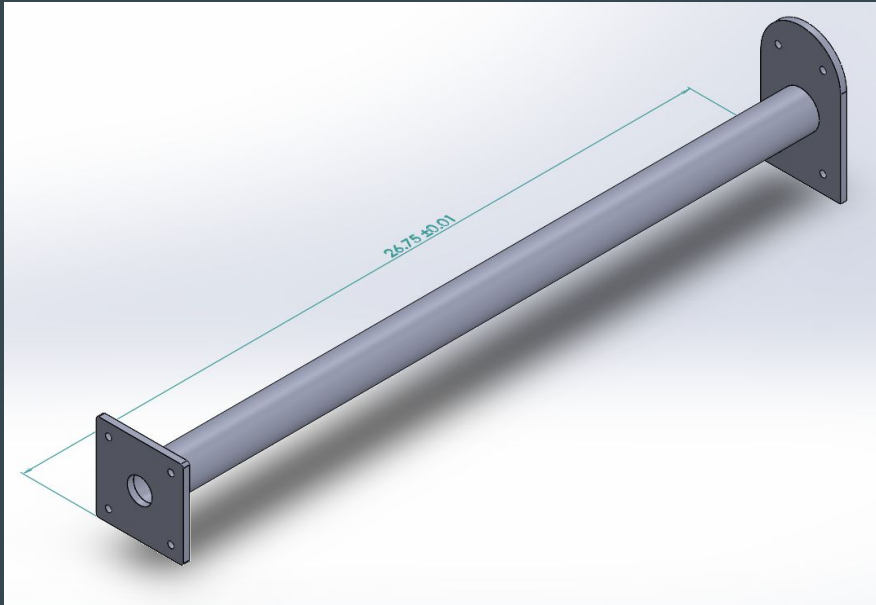


2019-2020 Endurance Extension

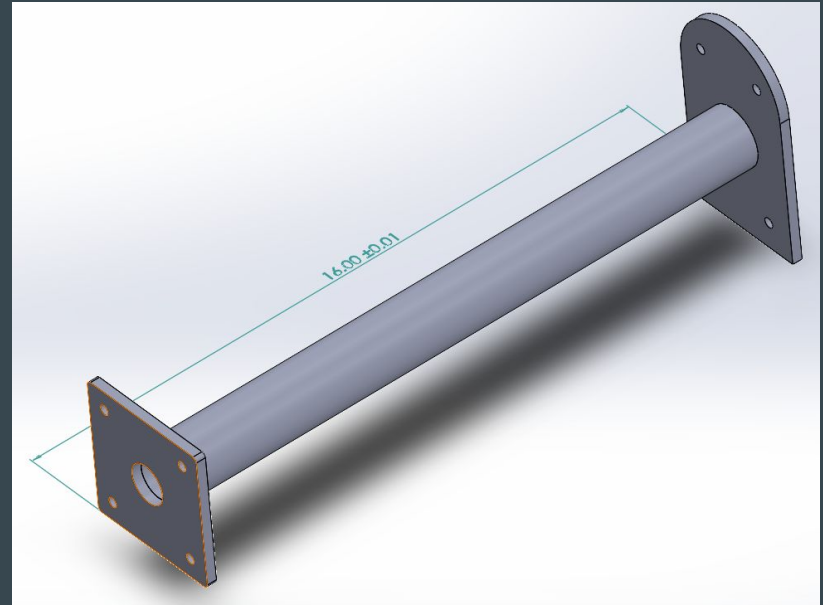


2019-2020 Sprint Configuration

Power Transfer Unit

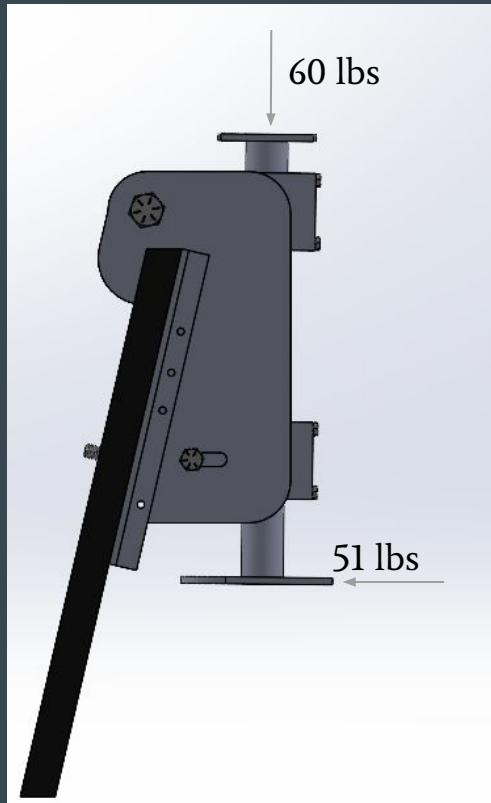


2020-2021 Endurance Housing



2020-2021 Sprint Housing

ANSYS Analysis



Spring Analysis (Left)

Element Size: 0.965 square inches

Element Type: Quad/Tri

Spring Analysis (Right)

Element Size: 1.0089 square inches

Element Type: Quad/Tri



Sprint Configuration Power Transfer Unit

A: Static Structural

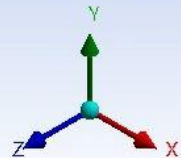
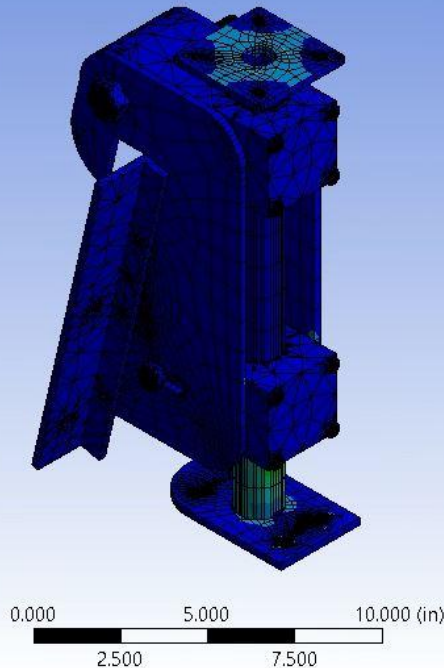
Equivalent Stress

Type: Equivalent (von-Mises) Stress

Unit: psi

Time: 1

11/24/2020 2:40 PM



ANSYS
2019 R1
ACADEMIC

Endurance Configuration Power Transfer Unit

A: Static Structural

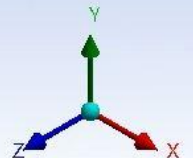
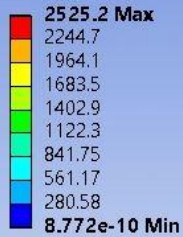
Equivalent Stress

Type: Equivalent (von-Mises) Stress

Unit: psi

Time: 1

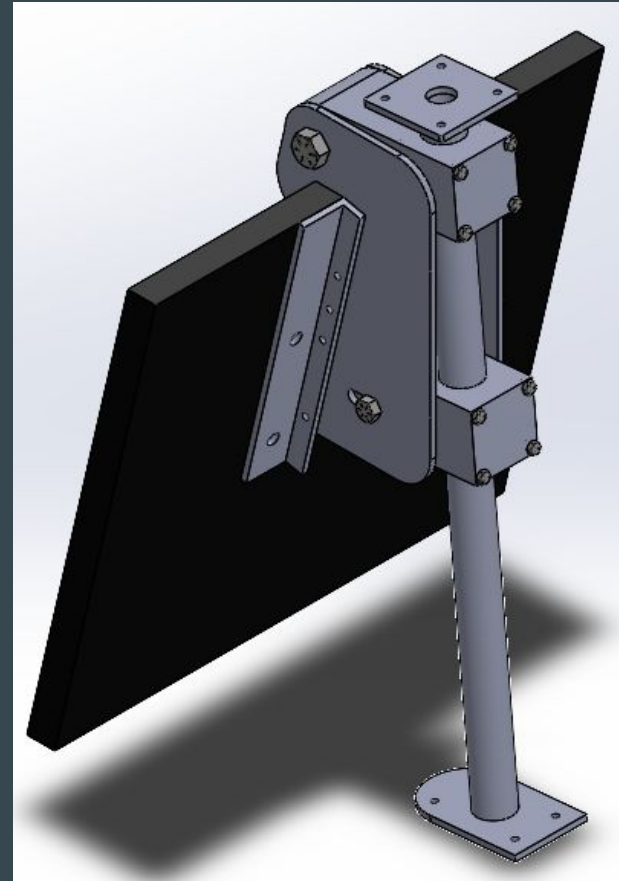
11/24/2020 3:26 PM



ANSYS
2019 R1
ACADEMIC

Future Plans

- Manufacturing
 - Motor Mounting Components
 - Sprint and Endurance Misdescriptions
- Testing
 - Integrated Designs
 - System Efficiency and Reliability

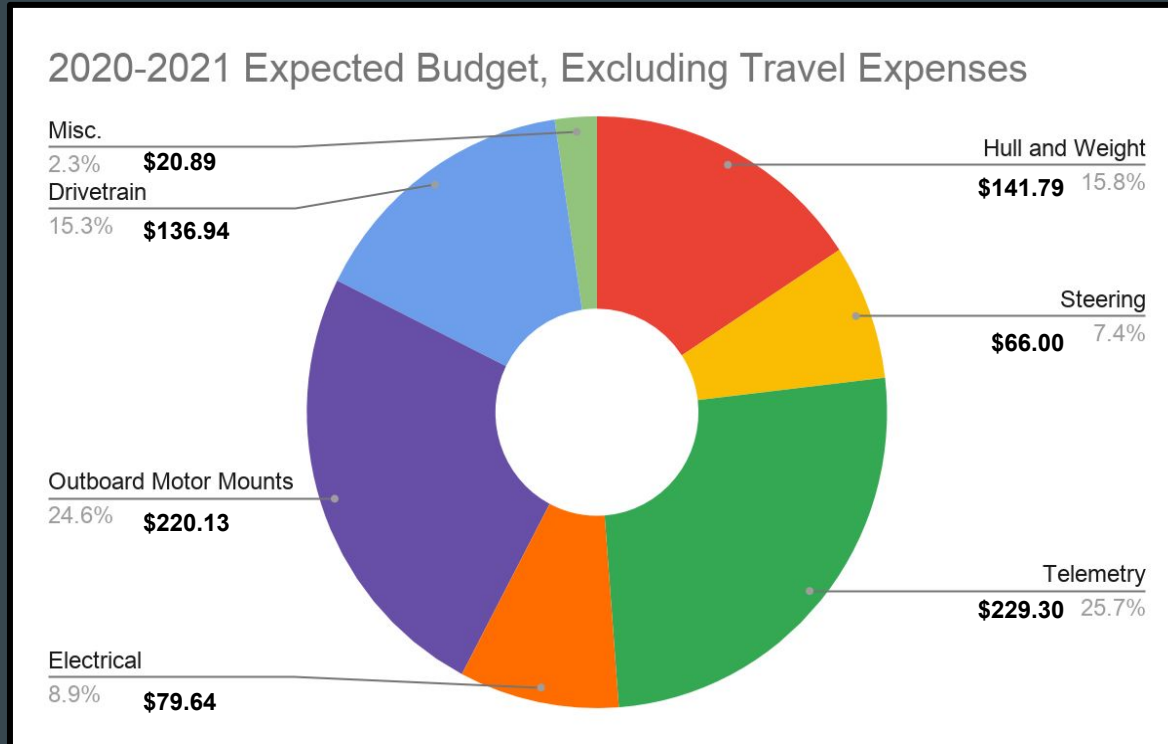




Project Management



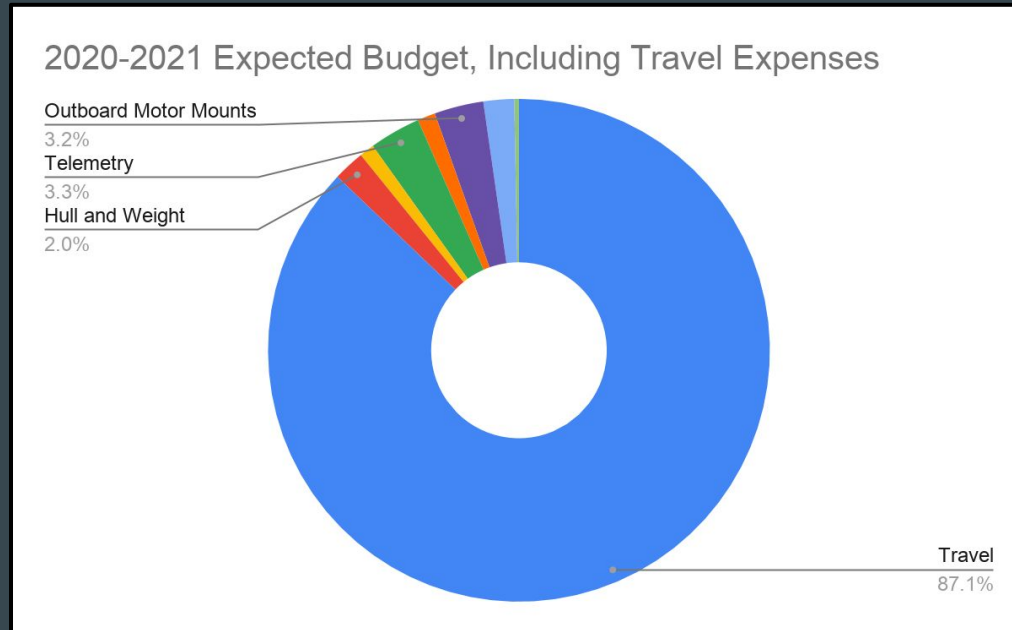
2021 Expected Budget



Budget Details

- Original Estimated Budget: \$5,450
 - Travel & Registration Fee: \$4,750
 - Project: \$700

- Current Estimated Budget: \$6,938.72
 - Travel & Registration Fee: \$6,045.03
 - Project: \$893.69



Media


TCNJ SOLAR SPLASH 2021



The College of New Jersey Solar Splash 2021

WHAT IS THE SOLAR SPLASH COMPETITION?


SOLAR SPLASH® is the World Championship of Collegiate Solar Boating, and the competition takes place over



TCNJ SolarSplash

HOME VIDEOS PLAYLISTS CHANNELS DISCUSSION ABOUT


Uploads



Solar Splash Team Time-lapse

2 views • 1 week ago

A timelapse of our time in the lab measuring and testing existing components.



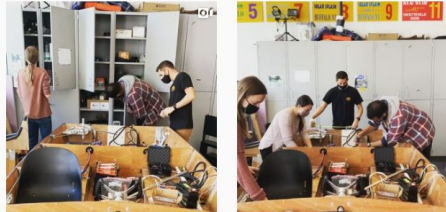
tcnjsolarsplash

Edit Profile

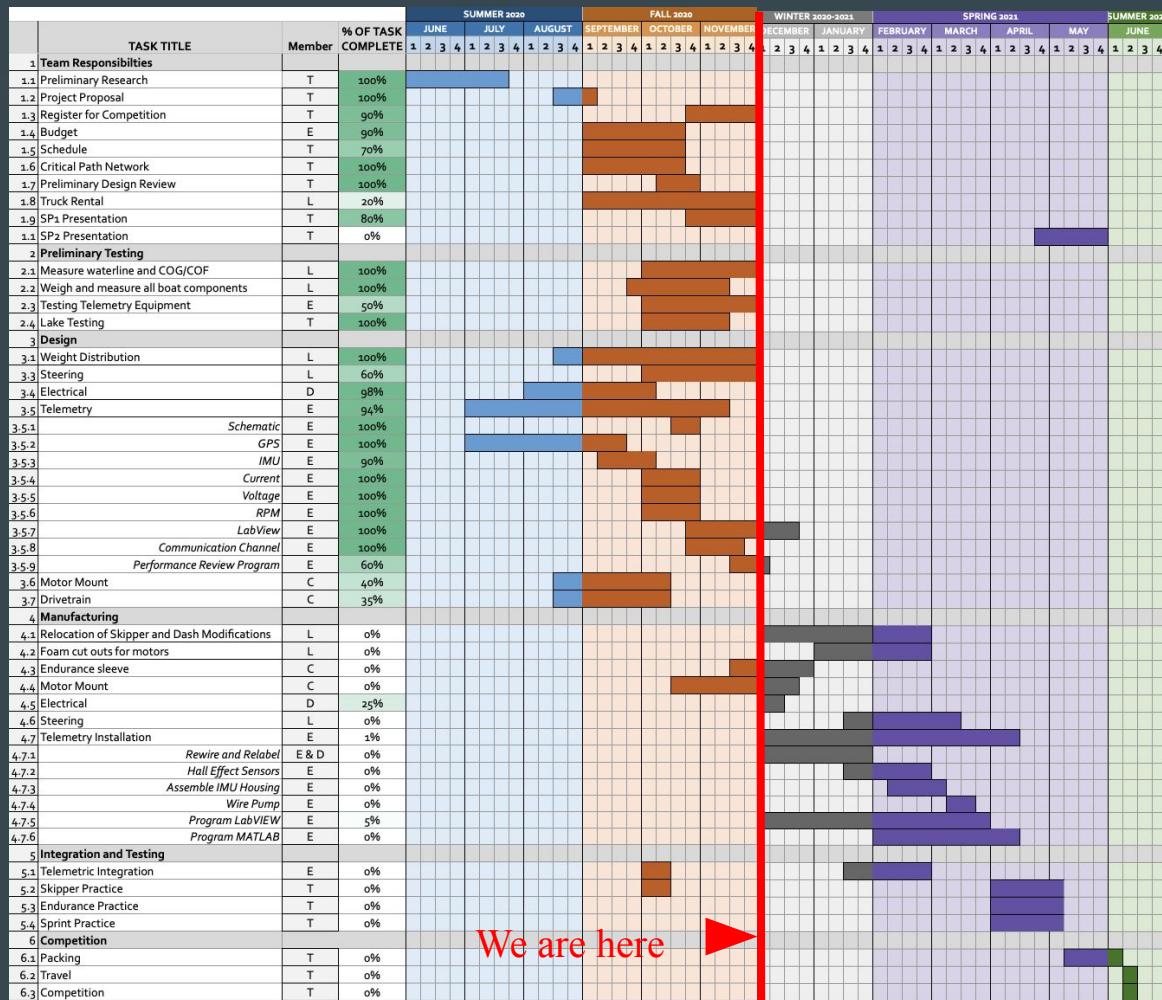
2 posts 38 followers 68 following

TCNJ Solar Splash
The College of New Jersey Solar Splash Competition Team
tcnjs21.weebly.com

POSTS IGTV SAVED TAGGED



GANTT Chart



We are here 



Solar Splash 2020-2021



Thank you Dr. Asper, Dr. Yan, Regina Cadillac, and the TCNJ School of Engineering

Questions?

Lauren DeSimone

Weight Distribution and Steering

Daniel Johnson

Electrical System

Eliza Sweet

Telemetry System

Christopher Taylor

Power Transmission System

